

These notes are almost entirely paraphrased from one of the references, with some extra details filled in by me where needed.

Many of the *products* we have in linear algebra are bilinear maps:

$$\begin{array}{ll} \text{scalar} & V \times F \rightarrow V & \text{inner} & \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R} \\ \text{cross} & \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}^3 & \text{matrix} & \mathbb{R}^{m \times k} \times \mathbb{R}^{k \times n} \rightarrow \mathbb{R}^{m \times n} \end{array}$$

Accordingly, we might think it important to require that any new product we define is also bilinear.

1 Background: Free Vector Space over a Set

Definition 1. The **free vector space** generated by a set X over field \mathbb{F} is the set of functions $X \rightarrow \mathbb{F}$ which are nonzero at only finitely many points,

$$\text{Free}(X) = \{f : X \rightarrow \mathbb{F} \mid f^{-1}(\mathbb{F} \setminus \{0\}) \text{ is finite}\}$$

The free vector space generated by X is a vector space when equipped with the standard operations of function addition and scalar multiplication:

$$(f + g)(x) = f(x) + g(x) \qquad (\alpha f)(x) = \alpha \cdot f(x)$$

The **standard basis** for $\text{Free}(X)$ is given by the indicator functions,

$$\text{Free}(X) = \text{span} \{ \mathbb{1}_a : X \rightarrow \{0, 1\} \mid a \in X \}$$

Example 1. The free vector space on $[n]$ over \mathbb{R} is isomorphic to \mathbb{R}^n .

The map $\iota : X \rightarrow \text{Free}(X)$ mapping $(a \in X) \mapsto \mathbb{1}_a$ is a bijection. Accordingly, $\text{Free}(x)$ may be regarded as the set of *formal* linear combinations of elements from X .

Remark 1. *The map ι is universal in the sense that if $\phi : X \rightarrow V$ is an arbitrary map from X to a vector space V , then there is a unique map ϕ^- such that the diagram below commutes:*

$$\begin{array}{ccc} X & \xrightarrow{\phi} & V \\ \downarrow \iota & \nearrow \phi^- & \\ \text{Free}(X) & & \end{array}$$

2 Direct Sums

For comparison to tensor products, the direct sum $V \oplus W$ of two vector spaces V, W by imposing a vector space structure on the Cartesian product $V \times W$, with addition and scaling defined by

$$\begin{aligned}(v_1, w_1) + (v_2, w_2) &= (v_1 + v_2, w_1 + w_2) \\ \alpha(v_1, w_1) &= (\alpha v_1, \alpha w_1)\end{aligned}$$

So that expressions like $v + w = (v, w)$ are well-defined, it is convenient to identify $v \in V$ with the element $(v, 0) \in V \times W$ in the larger space.

Proposition 1. *If $\mathcal{B}_V = \{v_1, \dots, v_m\}$ and $\mathcal{B}_W = \{w_1, \dots, w_n\}$ are bases for V and W , respectively, then $\mathcal{B}_V \cup \mathcal{B}_W$ is a basis for $V \oplus W$. Consequently,*

$$\dim(V \oplus W) = \dim V + \dim W$$

Proposition 2. *Let $T \in L(V, V)$ and $U \in L(W, W)$ be linear operators. There is a unique linear operator $(T \oplus U) : (V \oplus W) \rightarrow (V \oplus W)$ such that*

$$(T \oplus U)(v \oplus w) = (Tv) \oplus (Uw) \quad \text{for all } v \in V, w \in W$$

The matrix of $(T \oplus U)$ in any basis is block-diagonal, with blocks corresponding to the matrix representation of T and U respectively.

Proposition 3. *The direct sum satisfies the following useful properties:*

- I. $\det(T \oplus U) = (\det T)(\det U)$
- II. $\text{tr}(T \oplus U) = \text{tr}(T) \oplus \text{tr}(U)$

3 Tensor Products

(wikipedia) The tensor product of V and W is the vector space generated by the symbols $v \otimes w$ with $v \in V, w \in W$, in which the relations of bilinearity are imposed for the product operation \otimes and no other relations are assumed to hold. The tensor product space is thus the *freest* (or most general) such vector space, in the sense of having the *fewest* constraints.

Definition 2. The **tensor product** of two vector spaces V, W over \mathbb{F} is a vector space $V \otimes W$ over \mathbb{F} together with a bilinear map $V \times W \xrightarrow{\otimes} V \otimes W$ with the property that whenever $\mathcal{B}_V, \mathcal{B}_W$ are bases for V, W respectively, the set $\{v_i \otimes w_j \mid v_i \in \mathcal{B}_V, w_j \in \mathcal{B}_W\}$ gives a basis for $V \otimes W$.

The following theorem shows that the property in the definition need not be checked for all pairs of bases; just one pair is sufficient.

Theorem 1. *Let Y be a vector space and $\phi : V \times W \rightarrow Y$ be bilinear. Suppose there are bases $\mathcal{B}_V, \mathcal{B}_W$ for V, W respectively, such that $\phi(v \times w)$ is a basis for Y . Then the same holds for any pair of bases.*

3.1 Quotient Space Construction

Let V, W be vector spaces over \mathbb{F} . Following (Zakharevich 2015), our goal is to construct a vector space $V \otimes W$ such that for any vector space Z ,

$$\mathcal{L}(V \otimes W, Z) \cong \left\{ \begin{array}{c} \text{bilinear maps} \\ V \times W \rightarrow Z \end{array} \right\}$$

Step 1. Let $A = \text{Free}(V \times W)$ be the free vector space over \mathbb{F} on the product $V \times W$. We will demonstrate that

$$\mathcal{L}(A, Z) \cong \left\{ \begin{array}{c} \text{functions} \\ V \times W \rightarrow Z \end{array} \right\}$$

For $v \in V, w \in W$, define the notation $v \otimes w \equiv \mathbb{1}_{(v,w)} \in A$. A typical vector has the form $f = \sum_{k=1}^n \alpha_k (v_k \otimes w_k) \in A$. By linearity, observe that each $T \in \mathcal{L}(A, Z)$ is determined uniquely by its values on the standard basis, exposing a bijection between $\mathcal{L}(A, Z)$ and (nonlinear) functions $V \times W \rightarrow Z$.

$$Tf = T \left(\sum_{k=1}^n \alpha_k (v_k \otimes w_k) \right) = \sum_{k=1}^n \alpha_k T(v_k \otimes w_k)$$

Step 2. Since $\mathcal{L}(A, Z)$ represents arbitrary functions, we will construct $V \otimes W$ by shrinking A so that $\mathcal{L}(V \times W, Z)$ represents only the bilinear maps $V \times W \rightarrow Z$. For example, if $T \in \mathcal{L}(V \otimes W, Z)$ is a linear map, the following proof of bilinearity in the first argument

$$\begin{aligned} T((v_1 + v_2) \otimes w) &= T((v_1 \otimes w) + (v_2 \otimes w)) \\ &= T(v_1 \otimes w) + T(v_2 \otimes w) \end{aligned}$$

requires that $(v_1 + v_2) \otimes w$ and $(v_1 \otimes w) + (v_2 \otimes w)$ refer to the same element in $V \otimes W$. Starting from A , we can enforce this equivalence implicitly by defining $V \otimes W$ to be the quotient space A/A_0 , where

$$A_0 = \text{span} \left\{ \begin{array}{l} (v_1 + v_2) \otimes w - (v_1 \otimes w) - (v_2 \otimes w) \\ v \otimes (w_1 + w_2) - (v \otimes w_1) - (v \otimes w_2) \\ (\alpha v) \otimes w - \alpha(v \otimes w) \\ v \otimes (\alpha w) - \alpha(v \otimes w) \end{array} \middle| \begin{array}{l} \alpha \in F \\ v \in V, w \in W \end{array} \right\}$$

This choice was made so that each linear map $T \in \mathcal{L}(V \otimes W, Z)$ will satisfy¹

$$\begin{aligned} T((v_1 + v_2) \otimes w) &= T(v_1 \otimes w) + T(v_2 \otimes w) \\ T(v \otimes (w_1 + w_2)) &= T(v \otimes w_1) + T(v \otimes w_2) \\ T((\alpha v) \otimes w) &= T(\alpha(v \otimes w)) \\ T(v \otimes (\alpha w)) &= T(\alpha(v \otimes w)) \end{aligned}$$

As pointed out by (Purbhoo 2012), since $A = \text{Free}(V \times W)$ is the space of formal linear combinations of (v, w) pairs, A_0 is the space of those linear combinations that can be simplified to the zero vector using bilinearity. Accordingly, A/A_0 reduces A to a space where two expressions are equal iff one can be simplified to the other using bilinearity.

3.2 Bilinearity, Linearity, and Universality

We have achieved our goal that $\mathcal{L}(V \otimes W, Z)$ is equivalent to the set of bilinear maps $V \times W \rightarrow Z$, for any vector space Z . Notice that we can easily translate between linear maps $\mathcal{L}(V \otimes W, Z)$ and bilinear maps $\mathcal{L}(V \times W, Z)$.

Linear to Bilinear. Given a linear map $T \in \mathcal{L}(V \oplus W, Z)$, the map $(v, w) \mapsto T(v \oplus w)$ is bilinear, since

- I. the map $V \times W \mapsto V \oplus W$ given by $(v, w) \mapsto (v \oplus w)$ is bilinear
- II. the composition of a bilinear map and a linear map is bilinear

Bilinear to Linear. Given a bilinear map $f : V \times W \rightarrow Z$, define a linear map $g : A \rightarrow Z$ by $g(v \oplus w) \mapsto f(v, w)$, which is well-defined since $(v \oplus w)$ form a basis for A . Moreover, bilinearity of f implies that g vanishes on the four types of spanning vectors which define A_0 , so $g(A_0) = \{0\}$. Consequently, g descends to a well-defined linear map on A/A_0 .

We have just proven the following *universality* theorem, which states that every bilinear map is the composition of a linear map with the tensor product.

Theorem 2. (Universal Property) *Let V, W, M be vector spaces over \mathbb{F} . For each bilinear map $\phi : V \times W \rightarrow M$, there is a unique linear transformation $\bar{\phi} : V \otimes W \rightarrow M$ such that $\bar{\phi}(v \otimes w) = \phi(v, w)$ for all $v \in V, w \in W$. Moreover, every linear transformation in $\mathcal{L}(V \otimes W, M)$ arises in this way.*

More generally, every linear map $V_1 \otimes V_2 \otimes \cdots \otimes V_k \rightarrow M$ corresponds to a k -linear map $V_1 \times V_2 \times \cdots \times V_k \rightarrow M$.

3.3 Basis for the Tensor Product

Theorem 3. *Let $\{v_1, \dots, v_m\} \subset V$ be a basis for V and $\{w_1, \dots, w_n\} \subset W$. Then a basis for $V \otimes W$ is given by $\{v_i \otimes w_j \mid i \in [m], j \in [n]\}$.*

Proof. Notice that for any $v = \sum_{i=1}^m \alpha_i v_i$ and $w = \sum_{j=1}^n \beta_j w_j$,

$$\begin{aligned} v \otimes w &= \left(\sum_{i=1}^m \alpha_i v_i \right) \otimes w = \sum_{i=1}^m (\alpha_i v_i) \otimes w = \sum_{i=1}^m \alpha_i (v_i \otimes w) \\ &= \sum_{i=1}^m \alpha_i \left(v_i \otimes \sum_{j=1}^n \beta_j w_j \right) = \sum_{i=1}^m \sum_{j=1}^n \alpha_i \beta_j (v_i \otimes w_j) \end{aligned}$$

¹Technically, $(v \otimes w) \in V \otimes W$ stands for the equivalence class of $v \otimes w = \mathbb{1}_{(v,w)} \in A$.

Therefore $V \otimes W = \text{span}\{v_i \otimes w_j \mid i \in [m], j \in [n]\}$. For independence, we will explicitly construct an isomorphism between $V \otimes W$ and an arbitrary (mn) -dimensional vector space Z with basis vectors z_{ij} . There is a unique linear map from $\varphi : Z \rightarrow V \oplus W$ defined by $\varphi(z_{ij}) = (v_i \otimes w_j)$. To show φ is an isomorphism, we manually construct an inverse ϕ^{-1} . Consider the linear map $A \rightarrow Z$ mapping

$$v \otimes w = \sum_{i=1}^m \sum_{j=1}^n \alpha_i \beta_j (v_i \otimes w_j) \mapsto \sum_{i=1}^m \sum_{j=1}^n \alpha_i \beta_j z_{ij}$$

Notice that this map is zero on A_0 , hence the map is well-defined on A/A_0 . Moreover, it is surjective, since $v_i \otimes w_j \in A$, and inverse to ϕ . Hence ϕ is an isomorphism. \square

Corollary 1. $\dim(V \otimes W) = \dim V \times \dim W$

Remark 2. *Although $V \otimes W$ is spanned by the pure tensors $v \otimes w$, but not every vector can be written in this form. There exist elements of the tensor product which are not pure tensors.*

4 Computations with Tensor Products

The construction above is axiomatic, and defines tensors in terms of the properties they should satisfy. In practice, it is useful to actually identify the space $V \otimes W$ and the bilinear map $V \times W \rightarrow V \otimes W$ with some familiar object. Note that we must specify *both* the vector space we are identifying with $V \otimes W$ *and* the product that we are using to make this identification.

4.1 Familiar Examples

Example 2, (Matrices). Consider $V = \mathbb{F}^m$ and $W = \mathbb{F}^n$. To identify $V \otimes W$ with the space $\text{Mat}_{m \times n}(\mathbb{F})$ of matrices requires three steps:

- Define a vector space isomorphism $\phi : (\mathbb{F}^m \otimes \mathbb{F}^n) \rightarrow \text{Mat}_{m \times n}(\mathbb{F})$. Since these are finite-dimensional spaces with the same dimension, there is a natural isomorphism associated with any choice of bases.
- Define a bilinear map $\odot : \mathbb{F}^m \times \mathbb{F}^n \rightarrow \text{Mat}_{m \times n}(\mathbb{F})$ that explains how to construct a product element in $\text{Mat}_{m \times n}(\mathbb{F})$ from the two operands. This product should respect the isomorphism, $\phi(v \otimes w) = v \odot w$. For this example, one possible choice² is the outer product $v \odot w = vw^T$, meaning that identify vw^T with $v \otimes w$.
- Verify that $(\text{Mat}_{m \times n}(\mathbb{F}), \odot)$ is the tensor product of \mathbb{F}^n and \mathbb{F}^m by manually checking the basis condition in the definition. Indeed, choosing the standard basis $\{v_1, \dots, v_m\}$ for \mathbb{F}^m and $\{w_1, \dots, w_n\}$ for \mathbb{F}^n , it is clear that the matrices $\{v_i w_j^T\}$ form a basis for $\text{Mat}_{m \times n}(\mathbb{F})$.

Example 3, (Polynomials). Let $V = \mathbb{F}[x]$, the vector space of polynomials over one variable. Then $V \otimes V = \mathbb{F}[x, y]$ is the space of polynomials over two variables, with product $f(x) \odot g(y) = f(x)g(y)$. To verify, consider the basis $\mathcal{B} = \{1, x, x^2, \dots\}$ for V and observe that a basis for $\mathbb{F}[x, y]$ is

$$V \otimes V = \{x^a \otimes x^b \mid a, b \in \mathbb{N}\} \cong \{x^a y^b \mid a, b \in \mathbb{N}\}$$

²As (Purbhoo 2012) notes, there is more than one way to identify the tensor product of \mathcal{F}^m and \mathcal{F}^n with $\text{Mat}_{m \times n}$. They are all equivalent, in the same sense that $A \times B$ is equivalent to $B \times A$ for sets, but it is important to remember which choice was made.

Example 4. $V \otimes \mathbb{F} \cong V$, with product $v \otimes \alpha = \alpha v$. Choosing any basis $\{v_1, \dots, v_n\}$ for V and the basis $\{1\}$ for \mathbb{F} , we see that $\{v_k \otimes 1\}_{k=1}^n \cong \{v_k\}_{k=1}^n$ recovers the same basis for V .

4.2 Revealing Examples

So far, our discussion of tensor products has not produced any unfamiliar objects. The next several examples are more interesting.

Example 5. Let V, W be finite dimensional vector spaces and consider the dual space $V^* = L(V, \mathbb{F})$. Then, as a generalization of [Example 2](#), $V^* \otimes W = L(V, W)$, where $T \otimes w \in L(V, W)$ is defined to be the linear transformation $(f \otimes w)(v) = f(v) \cdot w$. If V and W are infinite-dimensional, then $V^* \otimes W = \{T \in L(V, W) \mid \dim(\text{im } T) < \infty\}$ is the set of finite-rank linear transformations in $L(V, W)$. This follows from the fact that $T \otimes w$ has rank one, and a linear combination of such transformations must have finite rank.

Example 6. Tensor products work well to distinguish spaces with different *units*. For example, if V is the space of velocity vectors with units (m/s) and T is the space T of time measurements with units s , then $V \otimes T$ is the space of displacement vectors, with units (m) . Although we can identify $V \cong \mathbb{R}^3$ and $T \cong \mathbb{R}$, this perspective emphasizes that V and T are fundamentally different.

Example 7. Let V, W, Z be vector spaces. Composition $(F, G) \mapsto F \circ G$ of linear maps is bilinear, giving rise to a linear map $\mathcal{L}(V, W) \otimes \mathcal{L}(W, Z) \rightarrow \mathcal{L}(V, Z)$.

4.3 Exotic Examples

4.4 Trace Functional

Let V be finite-dimensional. By [Example 5](#), $V^* \otimes V \cong L(V \rightarrow V)$. Notice that the evaluation functional $(f, v) \mapsto f(v)$ from $V^* \times V \rightarrow \mathbb{F}$ is bilinear.

Definition 3. The **trace** functional on $L(V \rightarrow V)$ is the unique linear transformation $\text{tr} : V^* \otimes V \rightarrow \mathbb{F}$ such that $\text{tr}(f \otimes v) = f(v)$ for all $v \in V$.

Example 8, (Contraction). Let V_1, V_2, \dots, V_k be f.d.v.s over \mathbb{F} . Suppose $V_i = V_j^*$ for some pair (i, j) . Consider the products $V = \bigotimes_{r=1}^n V_r$ and $W = \bigotimes_{r \neq i, j} V_r$. Using the trace, a **contraction** with respect to (i, j) is the linear transformation $\text{tr}_{ij} : V \rightarrow W$ satisfying

$$\text{tr}_{ij}(v_1 \otimes \cdots \otimes v_k) = \text{tr}(v_i \otimes v_j)(v_1 \otimes \cdots \otimes v_{i-1} \otimes v_{i+1} \otimes \cdots \otimes v_k)$$

5 Tensor Products & Linear Maps

5.1 Tensor Product of Linear Maps

Proposition 4. Let $T \in L(V_1, V_2)$ and $U \in L(W_1, W_2)$ be linear maps. There is a unique linear map $T \otimes U \in L(V_1 \otimes W_1 \rightarrow V_2 \otimes W_2)$ such that

$$(T \otimes U)(v \otimes w) = (Tv) \otimes (Uw) \quad \text{for all } v \in V, w \in W$$

Proof. Apply [Theorem 2](#) to the bilinear map $(v, w) \mapsto (Tv) \otimes (Uw)$. \square

5.2 Matrix Kronecker Products

Let $\mathcal{B}_V = \{v_1, \dots, v_m\} \in V$ and $\mathcal{B}_W = \{w_1, \dots, w_n\} \in W$ be bases for V, W respectively. Suppose $T \in L(V, V)$ has matrix $A \in \mathbb{F}^{n \times n}$.

$$\begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_m \end{bmatrix}_V \mapsto \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1m} \\ a_{21} & a_{22} & \cdots & a_{2m} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mm} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_m \end{bmatrix}_V$$

On the tensor product space, the map $(T \otimes I_W)(v \otimes w)$ applies A to v , leaving w untouched. With respect to the basis $v_i \otimes w_j$, this transformation is represented in matrix form by

$$\begin{bmatrix} a_{11}I & a_{12}I & \cdots & a_{1m}I \\ a_{21}I & a_{22}I & \cdots & a_{2m}I \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1}I & a_{m2}I & \cdots & a_{mm}I \end{bmatrix}$$

5.2.1 Kronecker Products with the Identity

Example 9. For $m = 2$ and $n = 3$, the Kronecker product matrix for $T \otimes I_W$ is

$$A \otimes I = \left[\begin{array}{ccc|ccc} a_{11} & 0 & 0 & a_{12} & 0 & 0 \\ 0 & a_{11} & 0 & 0 & a_{12} & 0 \\ 0 & 0 & a_{11} & 0 & 0 & a_{12} \\ \hline a_{21} & 0 & 0 & a_{22} & 0 & 0 \\ 0 & a_{21} & 0 & 0 & a_{22} & 0 \\ 0 & 0 & a_{21} & 0 & 0 & a_{22} \end{array} \right] \in \mathbb{R}^{6 \times 6}$$

Example 10. For $m = 2$ and $n = 3$, a linear map $U \in L(W, W)$ with matrix $B \in \mathbb{R}^{3 \times 3}$ acts on $V \otimes W$ according to the Kronecker product

$$I_2 \otimes B = \left[\begin{array}{ccc|ccc} b_{11} & b_{12} & b_{13} & 0 & 0 & 0 \\ b_{21} & b_{22} & b_{23} & 0 & 0 & 0 \\ b_{31} & b_{32} & b_{33} & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & b_{11} & b_{12} & b_{13} \\ 0 & 0 & 0 & b_{21} & b_{22} & b_{23} \\ 0 & 0 & 0 & b_{31} & b_{32} & b_{33} \end{array} \right] \in \mathbb{R}^{6 \times 6}$$

5.2.2 Properties of Kronecker Products

Proposition 5. The Kronecker product has the following properties.

- I. $(A_1 \otimes I)(A_2 \otimes I) = (A_1 A_2) \otimes I$

- II. $(I \otimes B_1)(I \otimes B_2) = I \otimes (B_1 B_2)$
- III. $(A \otimes I)(I \otimes B) = (I \otimes B)(A \otimes I) = (A \otimes B)$
- IV. $(A \otimes B)(v \otimes w) = (Av) \otimes (Bw)$

Proposition 6. *The Kronecker product has the following properties.*

- I. $(A \otimes B)^T = (A^T \otimes B^T)$
- II. $(A \otimes B)(C \otimes D) = (AC \otimes BD)$
- III. $(A \otimes B)^{-1} = A^{-1} \otimes B^{-1}$

Proposition 7. *(Trace and Determinant) The Kronecker product satisfies*

- I. $\det(A \otimes B) = (\det A)^m (\det B)^n$
- II. $\text{tr}(A \otimes B) = (\text{tr } A)(\text{tr } B)$

Example 11. (Quantum Mechanics, [3]) In quantum mechanics, each degree of freedom in a system is associated with a Hilbert space. For example, a free particle in three dimensions has three dynamical degrees of freedom p_x, p_y, p_z , corresponding to the momentum. The eigenstate of the full Hamiltonian is obtained by the tensor product of momentum eigenstates in each direction,

$$|p_x, p_y, p_z\rangle = |p_x\rangle \otimes |p_y\rangle \otimes |p_z\rangle$$

Example 12. An inner product $\langle \cdot, \cdot \rangle : V \times V \rightarrow \mathbb{F}$ is a bilinear map, so by [Theorem 2](#) there is a corresponding linear map $F \in L(V \otimes V, \mathbb{F})$ such that $\langle v_1, v_2 \rangle = F(v_1 \otimes v_2)$.

6 The Tensor Algebra

7 The Symmetric Tensor Algebra

The universal property for tensor products ([Theorem 2](#)) gives a natural correspondence between bilinear maps $V \times W \rightarrow M$ and linear maps $V \otimes W \rightarrow M$. By restricting our attention to linear maps with additional structure, it may be possible to view M as a quotient space of $V \otimes W$.

Definition 4. Let V be finite-dimensional over \mathbb{F} . Define $T^0(V) = \mathbb{F}$ and

$$T^k(V) \equiv V^{\otimes k} = V \otimes V \otimes \cdots \otimes V \quad \text{for any } k \in \mathbb{N}$$

Let $\mathcal{C}^k \preceq T^k(V)$ be the subspace spanned by all vectors

$$(x_1 \otimes \cdots \otimes x_i \otimes \cdots \otimes x_j \otimes \cdots \otimes x_k) - (x_1 \otimes \cdots \otimes x_j \otimes \cdots \otimes x_i \otimes \cdots \otimes x_k)$$

The k^{th} **symmetric power** of V is the quotient space $\text{Sym}^k(V) = T^k(V)/\mathcal{C}^k$. Elements of this space are written $x_1 x_2 \cdots x_k \cong \text{Proj}_{\text{Sym}^k(V)}(x_1 \otimes \cdots \otimes x_k)$.

Proposition 8. *The space $\text{Sym}^k(V)$ can be thought of as the space of degree- k polynomials over V , with product given by polynomial multiplication with respect to any given choice of basis. In particular, $\text{Sym}^k(V)$ has the following properties.*

- I. *The map $(x_1, \dots, x_k) \mapsto x_1 x_2 \cdots x_k$ from $V^k \mapsto \text{Sym}^k(V)$ is bilinear.*
- II. *$x_{\sigma(1)} x_{\sigma(2)} \cdots x_{\sigma(k)} = x_1 x_2 \cdots x_k$ for any permutation σ .*
- III. *If $\{v_1, \dots, v_n\}$ form a basis for V , then any element of $\text{Sym}^k(V)$ can be written as a polynomial of degree k in terms of the basis elements.*
- IV. *There is a bilinear map $\text{Sym}^a(V) \times \text{Sym}^b(V) \rightarrow \text{Sym}^{a+b}(V)$ sending $(x_1 x_2 \cdots x_a, y_1 y_2 \cdots y_b) \mapsto x_1 x_2 \cdots x_a y_1 y_2 \cdots y_b$.*

8 The Skew-Symmetric Tensor Algebra

Consider taking the tensor product $V \otimes V$ of V with itself. We can define a different type of tensor product by imposing the additional relation $v_1 \otimes v_2 = -v_2 \otimes v_1$. Define $A_1 = \text{span}\{A_0, (v_1 \otimes v_2) + (v_2 \otimes v_1)\}$, and write

$$V \wedge V = A/A_1$$

Pure tensors in $V \wedge V$ are written using the **wedge product** notation $v_1 \wedge v_2$ to emphasize that we have skew-symmetry.

Example 13, (Differential Forms). Consider the vector space $V = \mathcal{C}(U \rightarrow \mathbb{R})$ of continuous, real valued functions on an open set $U \subset \mathbb{R}^d$. The module of 1-forms on U is the module

$$\text{span}\{f_1 x_1 + \cdots + f_n dx_n\}$$

and the module of k -forms is the wedge product of this module with itself k times. Skew-symmetry ensures $dx_1 \wedge dx_2 = -dx_2 \wedge dx_1$.

Example 14, (Wedge Powers). If $\{v_1, \dots, v_n\}$ form a basis for V , then the skew-symmetric tensor product $V \wedge V$ is spanned by the vectors $v_i \wedge v_j$ with $i < j$. Write $\bigwedge^k V$ for the wedge product of V with itself k times. If $\dim V = n$, then $\dim \bigwedge^k V = \binom{\dim V}{k}$. In particular, $\dim \bigwedge^{\dim V} V = 1$.

Example 15, (Determinant). Let $T : V \rightarrow V$ be linear. Then

$$\bigwedge^{\dim V} T : \left(\bigwedge^{\dim V} V \right) \rightarrow \left(\bigwedge^{\dim V} V \right)$$

Since the dimension of each of the vector spaces on the right is one, this is just multiplication by a scalar! We can define the determinant as simply $\det T \equiv \bigwedge^{\dim V} T$.

8.1 Exterior Product

Definition 5. The **exterior algebra** over a vector space V is the collection

$$\Lambda(V) \equiv \bigwedge^0 V \oplus \bigwedge^1 V \oplus \bigwedge^2 V \oplus \cdots$$

The exterior forms a ring under the wedge product operation. A vector space over \mathbb{F} with the structure of a ring is called an **\mathbb{F} -algebra**.

Proposition 9. If $\alpha \in \bigwedge^a V$ and $\beta \in \bigwedge^b V$, then $\alpha \wedge \beta = (-1)^{ab}(\beta \wedge \alpha)$.

8.2 Linear Transformations

Theorem 4. Let V, M be vector spaces over \mathbb{F} . For any k -linear alternating function $\phi : V^k \rightarrow M$, there is a unique $\bar{\phi} : \bigwedge^k V \rightarrow M$ such that

$$\bar{\phi}(v_1 \wedge v_2 \wedge \cdots \wedge v_k) = \phi(v_1, v_2, \dots, v_k) \quad \text{for all } v_1, \dots, v_k \in V$$

Moreover, every linear map $\bigwedge^k V \rightarrow M$ arises in this manner.

Proposition 10. There is a bilinear map $\bigwedge^a V \times \bigwedge^b V \mapsto \bigwedge^{a+b} V$ such that

$$\left(\bigwedge_{i=1}^a v_i, \bigwedge_{j=1}^b w_j \right) \mapsto v_1 \wedge \cdots \wedge v_a \wedge w_1 \wedge \cdots \wedge w_b$$

8.3 Linear Independence

A square matrix has nonzero determinant if and only if its rows are linearly independent. The wedge product generalizes this idea.

Theorem 5. *A set of vectors $\{v_1, \dots, v_k\} \in V$ is linearly independent if and only if $v_1 \wedge v_2 \wedge \dots \wedge v_k \neq 0 \in \bigwedge^k V$.*

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