## Carathéodory's Theorem

**Theorem 1** (Carathéodory). Let  $X \subset \mathbb{R}^d$ . Then each point of conv(X) is a convex combination of at most d + 1 points of X.

*Proof.* Suppose there exists  $y \in \text{conv}(X)$  that cannot be expressed as a convex combination of fewer than  $m \ge d+2$  points in X. Then

$$y = \sum_{k=1}^{m} \lambda_k x_k$$
 with  $\sum_{k=1}^{m} \lambda_k = 1$  and  $\lambda_k > 0 \ \forall k$ 

The  $m \ge d+2$  points  $x_1, \ldots, x_m \in X$  must be affinely dependent, so

$$\sum_{k=1}^{m} \mu_k x_k = 0 \text{ with } \sum_{k=1}^{m} \mu_k = 0$$

Then, for any  $\alpha \in \mathbb{R}$ ,

$$y = y + 0 = \sum_{k=1}^{m} \lambda_k x_k + \alpha \sum_{j=1}^{m} \mu_k x_k = \sum_{k=1}^{m} (\lambda_k + \alpha \mu_k) x_k$$

The new coefficients  $\Lambda_k \equiv \lambda_k + \alpha \mu_k$  satisfy  $\sum_{k=1}^m \Lambda_k = 1$ . Choosing

$$j = \arg\min_{k:\mu_k > 0} \frac{\lambda_k}{\mu_k}$$

we further have  $\Lambda_k \geq 0$  for all k = 1, ..., m and  $\Lambda_j = 0$ . Hence y is a convex combination of fewer than m points of X, a contradiction!

From the proof it is clear that each point of  $\operatorname{conv}(X)$  for  $X \subset \mathbb{R}^d$  can be written as a convex combination of affinely independent points from X, of which there can be at most d+1. It follows immediately that the convex hull of a set  $X \subset \mathbb{R}^d$  is the union of all simplexes with vertices in X.

**Corollary 1.** Let  $X \subset \mathbb{R}^d$ . Each boundary point of conv(X) is a convex combination of d points from X.

Proof (from math.stackexchange.com/q/1786544). Let  $C = \operatorname{conv}(X)$ . For any  $x \in \partial C$ , there is a supporting hyperplane  $\mathcal{H}$  to C at x; that is, C is disjoint from an open half-space of  $\mathcal{H}$ . Observe that any representation of xas a convex combination of points from P cannot involve elements of P that are not in  $\mathcal{H}$ ; otherwise, the combination would lie outside the hyperplane. Therefore  $x \in \operatorname{conv}(P \cap \mathcal{H})$ . Applying Carathéodory's theorem to  $P \cap \mathcal{H}$ , considered as a subset of the (d-1)-dimensional space  $\mathcal{H}$ , we are done.  $\Box$ 

**Corollary 2.** The convex hull of a compact set  $K \subset \mathbb{R}^d$  is compact.

*Proof* (Danzer et al. 1963). Note that the unit simplex  $\Delta^d \subset \mathbb{R}^{d+1}$  is compact. Consider the function  $f : (\mathbb{R}^{d+1} \times K^{d+1}) \to K$  given by

$$f(\alpha_1, \dots, \alpha_{d+1}, x_1, \dots, x_{d+1}) = \sum_{k=1}^{d+1} \alpha_k x_k \in K$$

Since f is continuous and  $\Delta^d \times K^{d+1}$  is compact, the set  $f(\Delta^d \times K^{d+1})$  is compact. By Carathéodory's theorem,  $f(\Delta^d \times K^{d+1}) = \operatorname{conv}(K)$ .  $\Box$ 

#### Radon's Lemma



Figure 1: Two radon partitions.

**Theorem 2** (Radon's Lemma). Let  $A = \{a_1, \ldots, a_{d+2}\} \subset \mathbb{R}^d$ . Then there exist two disjoint subsets  $A_1, A_2 \subset A$  whose convex hulls have nonempty intersection.

*Proof* (Matoušek 2002). The d+2 points in  $A \subset \mathbb{R}^d$  must be affinely dependent, that is, there exist  $\lambda_1, \ldots, \lambda_{d+2} \in \mathbb{R}$  not all zero such that

$$\sum_{k=1}^{d+2} \lambda_k = 0 \text{ and } \sum_{k=1}^{d+2} \lambda_k a_k = 0$$

The sets  $P = \{k \mid \lambda_k > 0\}$  and  $N = \{k \mid \lambda_k < 0\}$  determine the desired subsets. Both are nonempty, so put  $A_1 = \{\lambda_k \mid k \in P\}$  and  $A_2 = \{\lambda_k \mid k \in N\}$ . Let  $S \equiv \sum_{k \in P} \lambda_k$ ; we also have  $S = -\sum_{k \in N} \lambda_k$ . Define

$$x \equiv \sum_{k \in P} \frac{\lambda_k}{S} a_k = \sum_{k \in N} \frac{-\lambda_k}{S} a_k$$

where equality holds because  $\sum_{k=1}^{d+2} \lambda_k a_k = \sum_{k \in P} \lambda_k a_k + \sum_{k \in N} \lambda_k a_k = 0$ . Both representations cast x as a convex combination, first of points from  $A_1$  then from  $A_2$ . Hence  $x \in \operatorname{conv}(A_1) \cap \operatorname{conv}(A_2)$ .

### Helly's Theorem

**Theorem 3** (Helly). Let  $C_1, C_2, \ldots, C_n \subset \mathbb{R}^d$  be convex, with  $n \geq d+1$ . If every d+1 of these sets intersect, then  $\bigcap_{i=1}^n C_i \neq \emptyset$ .

*Proof* (Matoušek 2002). For fixed d, we proceed by induction on n. The base case n = d + 1 is clear, so assume  $n \ge d + 2$  and that Helly's theorem holds for smaller n.

Consider convex  $C_1, \ldots, C_n \subset \mathbb{R}^d$  such that any d + 1 sets intersect. If we leave out any one of these sets  $C_i$ , the remaining sets have nonempty intersection  $a_i \in \bigcap_{j \neq i} C_j$  by the inductive assumption. Consider the  $n \geq$ d+2 points  $A = \{a_1, \ldots, a_n\} \subset \mathbb{R}^d$ . By Radon's lemma, there exist disjoint sets  $A_1, A_2 \subset A$  such that  $\operatorname{conv}(A_1) \cap \operatorname{conv}(A_2) \neq \emptyset$ . Choose a point x in the intersection. For any  $i \in [n]$ , either  $a_i \notin A_1$  or  $a_i \notin A_2$ . In the former case, each  $a_j \in A_1$  lies in  $C_i$ , so  $x \in \operatorname{conv}(A_1) \subset C_i$  by convexity. In the latter case we similarly have  $x \in \operatorname{conv}(A_2) \subset C_i$ . Therefore,  $x \in \bigcap_{i=1}^n C_i$ .

#### **Further Reading**

Compare proofs to (Matoušek 2002). For a comprehensive survey of applications see (Danzer et al. 1963). An elegant proof of Haar's theorem from approximation theory is given by (Pták 1958) via Carathéodory's theorem.

# References

- Ludwig Danzer, Branko Grünbaum, and Victor Klee. *Helly's Theorem* and its Relatives. American Mathematical Society Providence, RI, 1963.
- [2] Jiří Matoušek. Lectures on Discrete Geometry, volume 212. Springer Science & Business Media, 2002.
- [3] Vlastimil Pták. A remark on approximation of continuous functions. Czechoslovak Mathematical Journal, 8(2):251–256, 1958.

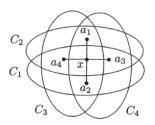


Figure 2: Illustration of Radon's proof of Helly's theorem for d = 2 and n = 4.